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- Lectures based on the following slides:
 - http://code.google.com/edu/submissions/mapreduce-minilecture/listing.html
- Authors:
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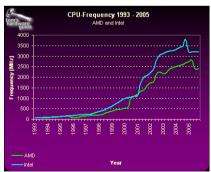
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Outline

- Part I: Motivations
 - Introduction
 - · Parallel vs. Distributed Computing
 - History of Distributed Computing
 - Parallelization and Synchronization
- Part II: MapReduce theory and implementation
 - Lisp/ML review (functional programming, map, fold)
 - MapReduce overview
 - Hadoop



Computer Speedup



Moore's Law: "The density of transistors on a chip doubles every 18 months, for the same cost" (1965)

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Scope of problems

- What can you do with 1 computer?
- What can you do with 100 computers?
- What can you do with an entire data center?

Distributed problems



• Rendering multiple frames of high-quality animation



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Distributed problems

 Simulating several hundred or thousand characters

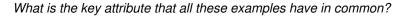




Happy Feet ® Kingdom Feature Productions; Lord of the Rings ® New Line Cinema, neither image is subject to the Creative Commons license applicable to the rest of the work.

Distributed problems

- Indexing the web (Google)
- Simulating an Internet-sized network for networking experiments (PlanetLab)
- Speeding up content delivery (Akamai)



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Parallel vs. Distributed

- Parallel computing can mean:
 - Vector processing of data
 - Multiple CPUs in a single computer
- Distributed computing is multiple CPUs across many computers over the network

A Brief History... 1975-85



- Parallel computing was favored in the early years
- Gradually more threadbased parallelism was introduced



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A Brief History... 1985-95



- "Massively parallel architectures" start rising in prominence
- Message Passing Interface (MPI) and other libraries developed
- Bandwidth was a big problem

A Brief History... 1995-Today



- Cluster/grid architecture increasingly dominant
- Special node machines eschewed in favor of COTS technologies
- Web-wide cluster software
- Companies like Google take this to the extreme

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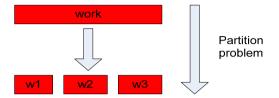


Parallelization & Synchronization



Parallelization Idea

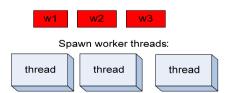
 Parallelization is "easy" if processing can be cleanly split into n units:



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Parallelization Idea (2)

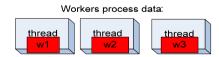




In a parallel computation, we would like to have as many threads as we have processors. e.g., a fourprocessor computer would be able to run four threads at the same time.

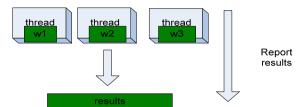
Parallelization Idea (3)





Parallelization Idea (4)





Parallelization Pitfalls



But this model is too simple!

- How do we assign work units to worker threads?
- What if we have more work units than threads?
- How do we aggregate the results at the end?
- How do we know all the workers have finished?
- What if the work cannot be divided into completely separate tasks?

What is the common theme of all of these problems?

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Parallelization Pitfalls (2)



- Each of these problems represents a point at which multiple threads must communicate with one another, or access a shared resource.
- Golden rule: Any memory that can be used by multiple threads must have an associated synchronization system!

What is Wrong With This?



Thread 1:	Thread 2:
void foo() {	void bar()
X++;	y++;
y = x;	x+=3;
}	}

If the initial state is y = 0, x = 6, what happens after these threads finish running?

Multithreaded = Unpredictability

■ Many things that look like "one step" operations actually take several steps under the hood:

```
Thread 2:
Thread 1:
void foo() {
                                  void bar() {
 eax = mem[x];
                                   eax = mem[v]:
 inc eax:
                                   inc eax:
 mem[x] = eax;
                                   mem[y] = eax;
 ebx = mem[x]:
                                   eax = mem[x]:
 mem[y] = ebx;
                                   add eax. 3:
                                   mem[x] = eax;
```

• When we run a multithreaded program, we don't know what order threads run in, nor do we know when they will interrupt one another.

Multithreaded = Unpredictability

This applies to more than just integers:

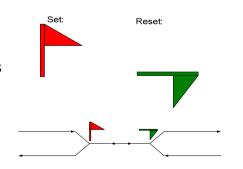
- Pulling work units from a gueue
- Reporting work back to master unit
- Telling another thread that it can begin the "next phase" of processing
- ... All require synchronization!

Synchronization Primitives

- A synchronization primitive is a special shared variable that guarantees that it can only be accessed atomically.
- Hardware support guarantees that operations on synchronization primitives only ever take one step

Semaphores

- A semaphore is a flag that can be raised or lowered in one step
- Semaphores were flags that railroad engineers would use when entering a shared track



Only one side of the semaphore can ever be red! (Can both be green?)





Semaphores

- set() and reset() can be thought of as lock() and unlock()
- Calls to lock() when the semaphore is already locked cause the thread to **block**.
- Pitfalls: Must "bind" semaphores to particular objects; must remember to unlock correctly

The "corrected" example



Condition Variables



- A condition variable notifies threads that a particular condition has been met
- Inform another thread that a queue now contains elements to pull from (or that it's empty – request more elements!)
- Pitfall: What if nobody's listening?

The final example



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```
Thread 1:
                              Thread 2:
void foo() {
                              void bar() {
 sem.lock():
                               sem.lock():
                               if(!fooDone)
 X++;
                                fooFinishedCV.wait(sem);
 V = X;
                               y++;
 fooDone = true:
                               x+=3;
 sem.unlock();
                               sem.unlock();
 fooFinishedCV.notify();
 Global vars: Semaphore sem = new Semaphore(); ConditionVar
 fooFinishedCV = new ConditionVar(); boolean fooDone = false;
```

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Too Much Synchronization? Deadlock

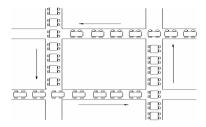


Synchronization becomes even more complicated when multiple locks can be used

Can cause entire system to "get stuck"

Thread A:

semaphore1.lock();
semaphore2.lock();
/* use data guarded by
 semaphores */
semaphore1.unlock();
semaphore2.unlock();



Thread B:

semaphore2.lock();
semaphore1.lock();
/* use data guarded by
 semaphores */
semaphore1.unlock();
semaphore2.unlock();

(Image: RPI CSCI.4210 Operating Systems notes)

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The Moral: Be Careful!



- Synchronization is hard
 - Need to consider all possible shared state
 - Must keep locks organized and use them consistently and correctly
- Knowing there are bugs may be tricky; fixing them can be even worse!
- Keeping shared state to a minimum reduces total system complexity

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Functional Programming Review



- Functional operations do not modify data structures: They always create new ones
- Original data still exists in unmodified form
- Data flows are implicit in program design
- Order of operations does not matter

Functional Programming Review



fun foo(I: int list) = sum(I) + mul(I) + length(I)

Order of sum() and mul(), etc does not matter – they do not modify *I*

Functional Updates Do Not Modify Structures



fun append(x, lst) =
let lst' = reverse lst in
reverse (x :: lst')

The append() function above reverses a list, adds a new element to the front, and returns all of that, reversed, which appends an item.

But it never modifies Ist!

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Functions Can Be Used As Arguments



fun DoDouble(f, x) = f (f x)

It does not matter what f does to its argument; DoDouble() will do it twice.

MapReduce



Motivation: Large Scale Data Processing



- Want to process lots of data (> 1 TB)
- Want to parallelize across hundreds/thousands of CPUs
- ... Want to make this easy

MapReduce



- Automatic parallelization & distribution
- Fault-tolerant
- Provides status and monitoring tools
- Clean abstraction for programmers

Programming Model



- Borrows from functional programming
- Users implement interface of two functions:
 - map (in_key, in_value) ->
 (out_key, intermediate_value) list
 - reduce (out_key, intermediate_value list) ->
 out_value list

map



- Records from the data source (lines out of files, rows of a database, etc) are fed into the map function as key*value pairs: e.g., (filename, line).
- map() produces one or more intermediate values along with an output key from the input.

reduce



- After the map phase is over, all the intermediate values for a given output key are combined together into a list
- reduce() combines those intermediate values into one or more final values for that same output key
- (in practice, usually only one final value per key)

Input key*value

(kéy 1,

values...)

map

(key 2,

values...)

intermediate

values

reduce

final kev 1

values

values)

== Barrier == : Aggregates intermediate values by output key

reduce

final kev 2

Parallelism



- map() functions run in parallel, creating different intermediate values from different input data sets
- reduce() functions also run in parallel, each working on a different output key
- All values are processed independently
- Bottleneck: reduce phase can't start until map phase is completely finished.



Example: Count word occurrences

```
map(String input_key, String input_value):
  // input_key: document name
  // input_value: document contents
  for each word w in input value:
    EmitIntermediate(w, "1");
reduce(String output_key, Iterator
  intermediate values):
  // output key: a word
  // output_values: a list of counts
  int result = 0;
  for each v in intermediate values:
    result. += ParseInt.(v):
 Emit(AsString(result));
```



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Input key*value

(kév 1

values...)

ntermediate values

map

(key 2,

values...)

reduce

final kev 3

values

key 3, intermediate

values

(key 3,

values...)

Example vs. Actual Source Code

- Example is written in pseudo-code
- Actual implementation is in C++, using a MapReduce library
- Bindings for Python and Java exist via interfaces
- True code is somewhat more involved (defines how the input key/values are divided up and accessed, etc.)

Locality



- Master program divvies up tasks based on location of data: tries to have map() tasks on same machine as physical file data, or at least same rack
- map() task inputs are divided into 64 MB blocks: same size as Google File System chunks

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Fault Tolerance



- Master detects worker failures
 - Re-executes completed & in-progress map() tasks
 - Re-executes in-progress reduce() tasks
- Master notices particular input key/values cause crashes in map(), and skips those values on re-execution.
 - Effect: Can work around bugs in third-party libraries!

Optimizations



- No reduce can start until map is complete:
 - A single slow disk controller can rate-limit the whole process
- Master redundantly executes "slow-moving" map tasks; uses results of first copy to finish

Why is it safe to redundantly execute map tasks? Wouldn't this mess up the total computation?

MapReduce Conclusions

- MapReduce has proven to be a useful abstraction
- Greatly simplifies large-scale computations at Google
- Functional programming paradigm can be applied to large-scale applications
- Fun to use: focus on problem, let library deal w/ messy details

Hadoop



- Apache Hadoop project develops open-source software for reliable, scalable, distributed computing
- MapReduce implementation
- Who uses Hadoop
 - Amazon
 - Adobe
 - Facebook
 - FOX
 - Google
 - IBM
 - LinkedIn
 - .

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