A logical view on scheduling in concurrency

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Introduction

Proofs as processes Processes as untyped proofs Why we should search further

Proofs as schedules

MLL with actions Soundness and completess

Uniform translations

Asynchronous translation Synchronous translation

Discussion

• The *formulae as types* approach:

formula \leftrightarrow type proof rules \leftrightarrow primitive instructions proof \leftrightarrow program normalization \leftrightarrow evaluation

■ The *proof search* approach:

formula \leftrightarrow program proof rules \leftrightarrow operational semantics proof construction \leftrightarrow execution proof \leftrightarrow successful run • The *formulae as types* approach:

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■ The *proof search* approach:

formula \leftrightarrow program proof rules \leftrightarrow operational semantics proof construction \leftrightarrow execution proof \leftrightarrow successful run

How can we fit *concurrency* into this framework? What is a proper *denotational semantics* for concurrency?







It is natural to represent it a language for interactive processes:

 $(\nu z) \big((\nu xy) (\bar{z} \langle xy \rangle | P | Q) | z(xy) R \big)$



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 $(vz)\big((vxy)(\bar{z}\langle xy\rangle \mid P \mid Q) \mid z(xy)R\big) \to (vxy)(P \mid Q \mid R)$

This idea was first implemented in

Gianluigi Bellin and Phil Scott On the π-calculus and linear logic Theoretical Computer Science, 1994 This idea was first implemented in

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Good points:

- Adequate representation of proof dynamics
- Study of information flow through proofs

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- Study of information flow through proofs

Limitations:

- Requires a lot of coding
- Touches processes of a very restricted form
- Does not provide much insight on the π-calculus

Axiom and cut:

$$u \to v \vdash u : \downarrow A^{\perp}, v : \uparrow A$$

 $\frac{P \vdash \Gamma, \vec{x} : A \quad Q \vdash \vec{x} : A^{\perp}, \Delta}{(\nu \vec{x})(P \mid Q) \vdash \Gamma, \Delta}$

Multiplicatives:

| Р | $\vdash \Gamma, \vec{x} : A \qquad Q \vdash \vec{y} : B, A$ | $\Delta \qquad P \vdash \Gamma, \vec{x} : A, \vec{y} : B$ |
|----------|---|---|
| | $P \mid Q \vdash \Gamma, \vec{xy} : A \in$ | $\overline{\otimes B, \Delta} \qquad \overline{P \vdash \Gamma, \overrightarrow{xy} : A \stackrel{\mathcal{R}}{\Rightarrow} B}$ |
| Actions: | $P \vdash \Gamma, \vec{x} : A$ | $P \vdash \Gamma, \vec{x} : A$ |
| | $u(\vec{x}).P \vdash \Gamma, u : \downarrow A$ | $\overline{u}(\vec{x}).P \vdash \Gamma, u: \uparrow A$ |

Exponentials for replication, additives for external choice.

The system on the previous slide was introduced in

EB

A concurrent model for linear logic MFPS 2006

but was found to be strongly related to

Nobuko Yoshida, Martin Berger, and Kohei Honda Strong normalisation in the π-calculus LICS 2001

Bellin and Scott's encoding decomposes inside. Independently developped:

Luís Caires and Frank Pfenning

Session types as intuitionistic linear propositions Concur 2010

appears as a fragment.

Typing processes in linear logic

Good things:

- Typed processes cannot diverge or deadlock.
- Typing is preserved by reduction up to structural congruence.
- Extends to differential linear logic through "algebraic" extensions of process calculi.
- Induces translations of the λ -calculus into the π -calculus.

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- Induces translations of the λ -calculus into the π -calculus.

Shortcomings:

- Typed processes are essentially functional.
- Only *top-level* cut elimination matches execution.
- Many well-behaved interaction patterns are not typable.

$a.\overline{b} \mid b.\overline{c} \mid \overline{a.c.d}$

Translating *all* processes requires an untyped proof language.

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- Standard linear logic is not an option because of confluence.
- Differential linear logic allows for explicit non-determinism:

 $\frac{P \vdash \Gamma \quad Q \vdash \Gamma}{P + Q \vdash \Gamma}$

Its rules allow for an implementation of all processes.

Thomas Ehrhard and Olivier Laurent Interpreting a finitary π-calculus in differential interaction nets Concur 2007

Good points:

- Does provide insights on concurrent processes
- Relates algebraic proof semantics and process semantics

Good points:

- Does provide insights on concurrent processes
- Relates algebraic proof semantics and process semantics
 Limitations:
 - Not clear how to get logic back into the process language
 - Prefixing is only described very indirectly:

 π -calculus \longrightarrow solos calculus \longrightarrow differential nets

Proof normalization, aka *cut elimination*:

- the meaning of a proof is in its normal form,
- normalization is an *explicitation* procedure,
- it really wants to be confluent.

Interpretation of concurrent processes:

- the meaning is the *interaction*, the final (irreducible) state is less relevant,
- a given process may behave very differently depending on scheduling decisions.

Some information is missing.

The principles of our new interpretation:

formula \leftrightarrow type of interaction proof rules \leftrightarrow primitives for building schedules proof \leftrightarrow schedule for a program normalization \leftrightarrow evaluation according to a schedule

This is not exactly:

- Curry-Howard for processes: proofs are not programs, but behaviours of programs
- Proof search:

the dynamics is not in proof construction but in cut-elimination but a sort of middle ground in between. The first step: a logical description of all executions.

EB and Virgile Mogbil

Proofs as executions IFIP TCS 2012 — Chocola 14/3/2013

How we proceed:

- Back to CCS, for now.
- Slightly change the logic to represent actions explicitly.
- Match each execution with cut elimination of some proof.

We consider a CCS-style process calculus.

 $P,Q := 1 \qquad \text{inaction} \\ a.P \qquad \text{perform } a \text{ then do } P \\ P \mid Q \qquad \text{interaction of } P \text{ and } Q \\ ((va)P \qquad \text{scope restriction})$

There is one source of non-determinism: the pairing of associated events upon synchronization

$$a.P \mid a.Q \mid \bar{a}.R \rightarrow \begin{cases} a.P \mid Q \mid R \\ P \mid a.Q \mid R \end{cases}$$

Types of schedules:

| $A,B := \langle a \rangle A$ | do action <i>a</i> and then act as <i>A</i> |
|--|--|
| $A \otimes B$ | two independent parts, one as A , the other as B |
| A 🎙 B | A and B are both exhibited, but correlated |
| α | an unspecified behaviour (type variable) |
| α^{\perp} | something that can interact with $lpha$ |
| $(\forall \alpha A, \exists \alpha A)$ | quantification over behaviours) |

Transforming schedules:

 $A_1, \dots, A_n \vdash B$

behave as type B in association with processes behaving as each type A_i

Two-sided version.

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 $\vdash A_1^{\perp},...,A_n^{\perp},B$

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Duality: $(A \otimes B)^{\perp} = A^{\perp} \mathfrak{B} B^{\perp}, (\langle a \rangle A)^{\perp} = \langle \overline{a} \rangle (A^{\perp}).$

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| (∀ <i>αA</i> , 1 | ΞαΑ |

do action *a* and then act as *A* two independent parts, one as *A*, the other as *B A* and *B* are both exhibited, but correlated an unspecified behaviour (type variable) something that can interact with α quantification over behaviours)

Transforming schedules:

 $P \vdash A_1^{\perp}, ..., A_n^{\perp}, B$

P can behave as type *B* in association with processes behaving as each type A_i

Duality: $(A \otimes B)^{\perp} = A^{\perp} \mathfrak{B} B^{\perp}, (\langle a \rangle A)^{\perp} = \langle \overline{a} \rangle (A^{\perp}).$

MLL with actions Proof rules

Axiom and cut:

$$\frac{1}{1 \vdash A^{\perp}, A} \qquad \frac{P \vdash \Gamma, A \quad Q \vdash A^{\perp}, \Delta}{P \mid Q \vdash \Gamma, \Delta}$$

Multiplicatives:

$$\frac{P \vdash \Gamma, A \quad Q \vdash B, \Delta}{P \mid Q \vdash \Gamma, A \otimes B, \Delta} \qquad \frac{P \vdash \Gamma, A, B}{P \vdash \Gamma, A \ \mathfrak{P} B}$$
Actions:
$$\frac{P \vdash \Gamma, A}{a.P \vdash \Gamma, \langle a \rangle A} \qquad \frac{P \vdash \Gamma, A \quad \alpha \notin \operatorname{fv}(\Gamma)}{P \vdash \Gamma, \forall \alpha A} \qquad \frac{P \vdash \Gamma, A[B/\alpha]}{P \vdash \Gamma, \exists \alpha A}$$

Ceci n'est pas un système de types.

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MLLa admits proof nets: those of MLL plus unary links for modalities.



- Modality rules commute with everything, indeed $A \simeq \langle a \rangle A$.
- Correctness criteria: the same as MLL.
- We avoid second-order quantification for simplicity, we stick with parametricity in type variables.

The following proof is an annotation for $a.\bar{b} | b.\bar{c} | \bar{a}.c.d$:



If we use boxes, we have a "head cut elimination" matching execution: $a.\overline{b} \mid b.\overline{c} \mid \overline{a.c.d}$

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If we use boxes, we have a "head cut elimination" matching execution:

 $a.\overline{b} \mid b.\overline{c} \mid \overline{a.c.d} \to \overline{b} \mid b.\overline{c} \mid c.d \to \overline{c} \mid c.d \to d$

Theorem (Soundness)

Typing is preserved by reduction, head cut-elimination steps correspond to execution steps.

The definition of "head" cut-elimination requires boxes for modality rules, to keep track of prefixing.

Theorem (Completeness)

For every lock-avoiding run $P_1 \rightarrow ... \rightarrow P_n$ there are annotations such that $\pi_1 : P_1 \vdash \Gamma \rightarrow ... \rightarrow \pi_n : P_n \vdash \Gamma$ is a cut elimination sequence.

Every execution correspond to some proof:

- the proof provides a schedule (pairing between actions),
- cut elimination provides actual execution.

These proofs have very different types:

- the type is deduced from the execution, it describes control flow according a particular schedule;
- the type decsribes a way for a process interacts with its environment,
- no most general type.

Step 2: make things more uniform.

 $a.P \mid Q \mid \overline{a}.R \rightarrow P \mid Q \mid R$



 $a.P \mid Q \mid \bar{a}.R \rightarrow P \mid Q \mid R$



 $a.P \mid Q \mid \bar{a}.R \rightarrow P \mid Q \mid R$



 $a.P \mid Q \mid \bar{a}.R \rightarrow P \mid Q \mid R$



 $a.P \mid Q \mid \bar{a}.R \rightarrow P \mid Q \mid R$

on may need some plumbing:



The type of $\bar{a}.R$ depends on that of Q, even if only Q only interacts with P.

```
a.P \mid Q \mid \overline{a}.R \rightarrow P \mid Q \mid R
```

on may need some plumbing:



The construction does not depend on the types: *parametricity in* α one can always proceed the same way.

Definition

Terms of MCCS are translated into MLLa formulas as follows:

$$\begin{bmatrix} 1 \end{bmatrix}_{A} := \forall \alpha \ \alpha^{\perp} \ \mathfrak{P} \ \alpha$$

$$\begin{bmatrix} P \mid Q \end{bmatrix}_{A} := \begin{bmatrix} P \end{bmatrix}_{A} \otimes \begin{bmatrix} Q \end{bmatrix}_{A}$$

$$\begin{bmatrix} a.P \end{bmatrix}_{A} := \forall \alpha \ \langle a \rangle \alpha^{\perp} \ \mathfrak{P} \ (\begin{bmatrix} P \end{bmatrix}_{A} \otimes \alpha) \qquad = \forall \alpha \ \langle \bar{a} \rangle \alpha \multimap (\begin{bmatrix} P \end{bmatrix}_{A} \otimes \alpha)$$

$$\begin{bmatrix} \bar{a}.P \end{bmatrix}_{A} := \forall \beta \ (\begin{bmatrix} P \end{bmatrix}_{A} \otimes \beta^{\perp}) \ \mathfrak{P} \ \langle \bar{a} \rangle \beta \qquad = \forall \beta \ (\begin{bmatrix} P \end{bmatrix}_{A} \multimap \beta) \multimap \langle a \rangle \beta$$

Name hiding is left aside for now.

Fact

For every *P*, the type $[P]_A$ has one cut-free proof $(P)_A$.

For actions:



"Asynchronous" version

Theorem

There is an execution $P \rightarrow^* 1$ if and only if $[P]_A \multimap [1]_A$ is provable in *MLL* (without modality rules).

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From execution to implication:

each execution step is provable.

From implication to execution:

find a first interaction,

exploiting the correctness criterion for a proof of $[P]_A \multimap [1]_A$.

"Asynchronous" version: finding the first action



"Asynchronous" version: finding the first action



"Asynchronous" version: finding the first action



"Asynchronous" version: finding the first action



"Asynchronous" version: finding the first action

Suppose there is some proof of $[a_1.P_1 | ... | a_n.P_n]_A \multimap [1]_A$ but no two a_i can synchronize:



Impossible because of acyclicity!

Definition

Terms of MCCS are translated into MLLa formulas as follows:

$$\begin{bmatrix} 1 \end{bmatrix}_{S} := \forall \alpha \ \alpha^{\perp} \ \mathfrak{P} \ \alpha \qquad = \forall \alpha \ \alpha \multimap \alpha$$

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$$\begin{bmatrix} a.P \end{bmatrix}_{S} := \forall \alpha \ \langle a \rangle (\alpha^{\perp} \ \mathfrak{P} \ (\begin{bmatrix} P \end{bmatrix}_{S} \otimes \alpha)) \qquad = \forall \alpha \ \langle a \rangle (\alpha \multimap (\begin{bmatrix} P \end{bmatrix}_{S} \otimes \alpha))$$

$$\begin{bmatrix} \bar{a}.P \end{bmatrix}_{S} := \forall \beta \ \langle \bar{a} \rangle (\begin{bmatrix} P \end{bmatrix}_{S} \otimes \beta^{\perp}) \ \mathfrak{P} \ \beta \qquad = \forall \beta \ \langle a \rangle (\begin{bmatrix} P \end{bmatrix}_{S} \multimap \beta) \multimap \beta$$

Spot the difference!

Fact

For every *P*, the type $[P]_{S}$ has one cut-free proof $(P)_{S}$.

For actions:



"Synchronous" version

Theorem

There is an execution $P \rightarrow^* Q$ if and only if $[P]_S \multimap [Q]_S$ is provable in *MLL* (without modality rules).

"Synchronous" version

Theorem

There is an execution $P \to Q$ if and only if $[P]_S \multimap [Q]_S$ is provable in *MLL* (without modality rules).

From execution to implication:



proves $\lceil (a.P \mid \bar{a}.Q) \mid R \rceil_{S} \multimap \lceil (P \mid Q) \mid R \rceil_{S}$

"Synchronous" version

Theorem

There is an execution $P \rightarrow^* Q$ if and only if $[P]_S \multimap [Q]_S$ is provable in *MLL* (without modality rules).

From execution to implication:

each execution step is provable.

From implication to execution:

- take a proof of $[P]_S \rightarrow [Q]_S$
- cut it against (P)_S, eliminate the cut
- read back process terms from intermediate steps

Pairings

Definition

A pairing is an association between occurrences of dual actions

$$p_1:$$

$$p_2:$$

$$P = a.b.A \mid \overline{a.c.B} \mid \overline{b.c.C} \mid \overline{a.c}$$

Definition

A *determinisation* of *P* along a pairing *p* is a renaming $\partial_p(P)$ of actions in *P* where names are equal only for related actions.

$$\begin{aligned} \partial_{p_1}(P) &= a_1.b_1.\partial(A) \mid \bar{a}_2.c_1.\partial(B) \mid \bar{b}_2.\bar{c}_2.\partial(C) \mid a_2.\bar{c}_1 \\ \partial_{p_2}(P) &= a_1.b_1.\partial(A) \mid \bar{a}_1.c_1.\partial(B) \mid \bar{b}_1.\bar{c}_1.\partial(C) \mid a_2.\bar{c}_2 \end{aligned}$$

Facts about pairings:

- each run induces a pairing
- runs are equivalent up to permutation of independent events iff they induce the same pairing
- if *p* is a *consistent* pairing of *P* then *p* is the unique maximal consistent pairing of ∂_p(*P*)

Hence pairings are *execution schedules* and determinized terms represent them inside the process language.

Observation

Pairings are related to placements of axiom links in proofs of $[P]_A \multimap [1]_A$.

Some points deserve more investigation:

Replication: everything extends smoothly by setting $[!P]_A = ![P]_A$.

Choice: additives are the natural option

Name hiding: the situation is not obvious

- use quantifiers? existential? nabla?
- partial scheduling?
 (va)P is P with some proof that decides what happens on a

Name passing: need to fix hiding first!

Current state of affairs:

- A logical description of scheduling in processes
- Explicitation of *control flow* through processes
- Hints for a new study of prefixing in processes

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Ongoing questions:

- Which semantics for the logic of schedules? coherence spaces for MLLa, etc
- CPS-like interpretation of processes?
 the translation of actions is a kind of double negation
- A logical account on π-to-solos encoding? by relating to other systems

Work in progress...