

Network Economics

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Lecture 2: Incentives in online systems I: free riding and effort elicitation

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Fall 2016

References

- Main:
 - N. Nisam, T. Roughgarden, E. Tardos and V. Vazirani (Eds). “Algorithmic Game Theory”, CUP 2007. Chapters 23 (see also 27).
 - Available online:
http://www.cambridge.org/journals/nisan/downloads/Nisan_Non-printable.pdf
- Additional:
 - Yiling Chen and Arpita Gosh, “Social Computing and User Generated Content,” EC’13 tutorial
 - Slides at http://www.arpitaghosh.com/papers/ec13_tutorialSCUGC.pdf and http://yiling.seas.harvard.edu/wp-content/uploads/SCUGC_tutorial_2013_Chen.pdf
 - M. Chiang. “Networked Life, 20 Questions and Answers”, CUP 2012. Chapters 3-5.
 - See the videos on www.coursera.org

Outline

1. Introduction
2. The P2P file sharing game
3. Free-riding and incentives for contribution
4. Hidden actions: the principal-agent model

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Online systems

- Resources
 - P2P systems
- Information
 - Ratings
 - Opinion polls
- Content (user-generated content)
 - P2P systems
 - Reviews
 - Forums
 - Wikipedia
- Labor (crowdsourcing)
 - AMT
- In all these systems, there is a need for users contribution

P2P networks

- First ones: Napster (1999), Gnutella (2000)
 - Free-riding problem
- Many users across the globe self-organizing to share files
 - Anonymity
 - One-shot interactions
 - Difficult to sustain collaboration
- Exacerbated by
 - Hidden actions (nondetectable defection)
 - Cheap pseudonyms (multiple identities easy)

Incentive mechanisms

- Good technology is not enough
- P2P networks need incentive mechanisms to incentivize users to contribute
 - Reputation (KaZaA)
 - Currency (called scrip)
 - Barter (BitTorrent) – direct reciprocity

Extensions

- Other free-riding situations
 - E.g., mobile ad-hoc networks, P2P storage
- Rich strategy space
 - Share/not share
 - Amount of resources committed
 - Identity management
- Other applications of incentives / reputation systems
 - Online shopping, forums, etc.

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The P2P file-sharing game

- Peer
 - Sometimes download \rightarrow benefit
 - Sometimes upload \rightarrow cost
- One interaction \sim prisoner's dilemma

	C	D
C	2, 2	-1, 3
D	3, -1	0, 0

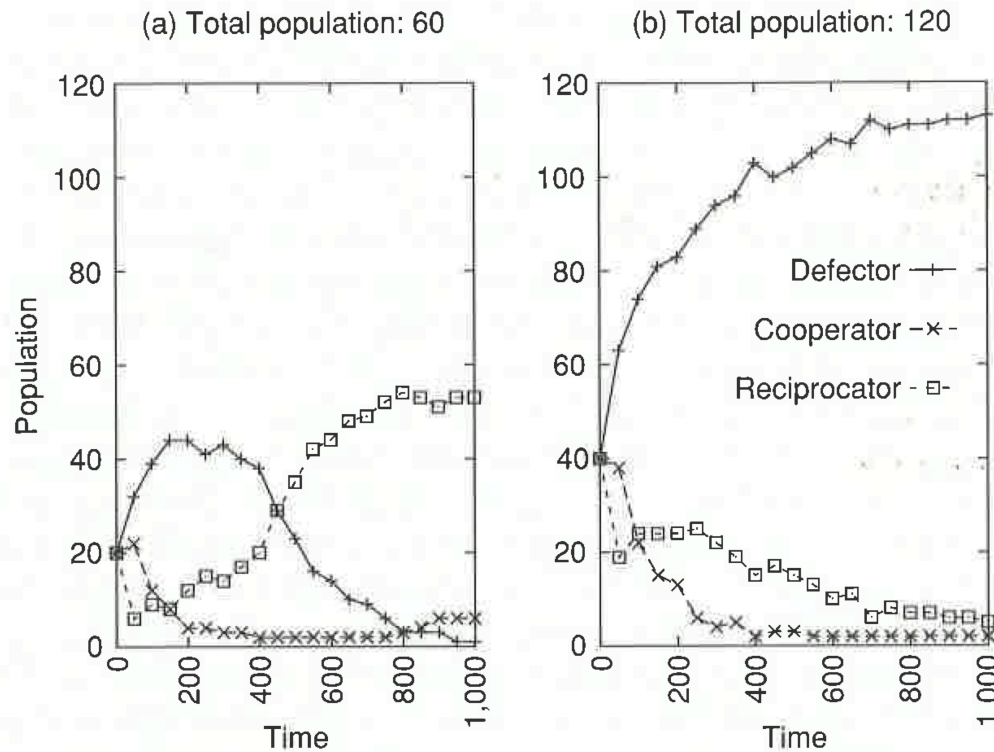
Prisoner's dilemma

- Dominant strategy: D
- Socially optimal (C, C)
- Single shot leads to (D, D)
 - Socially undesirable
- Iterated prisoner's dilemma
 - Tit-for-tat yields socially optimal outcome

	C	D
C	2, 2	-1, 3
D	3, -1	0, 0

P2P

- Many users, random interactions



Feldman et al. 2004

- Direct reciprocity does not scale

P2P

- Direct reciprocity
 - Enforced by Bittorrent at the scale of one file but not over several files
- Indirect reciprocity
 - Reputation system
 - Currency system

How to treat new comers

- P2P has high turnover
- Often interact with stranger with no history
- TFT strategy with C with new comers
 - Encourage new comers
 - BUT Facilitates whitewashing

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Reputation

- Long history of facilitating cooperation (e.g. eBay)
- In general coupled with service differentiation
 - Good reputation = good service
 - Bad reputation = bad service
- Ex: KaZaA

Trust

- EigenTrust (Sep Kamvar, Mario Schlosser, and Hector Garcia-Molina, 2003)
 - Computes a global trust value of each peer based on the local trust values
- Used to limit malicious/inauthentic files
 - Defense against pollution attacks

Attacks against pollution systems

- Whitewashing
 - Sybil attacks
 - Collusion
 - Dishonest feedback
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- See next lecture...
 - This lecture: how reputation helps in eliciting effort

A minimalist P2P model

- Large number of peers (players)
- Peer i has type θ_i (\sim “generosity”)
- Action space: contribute or free-ride
- x : fraction of contributing peers
 $\rightarrow 1/x$: cost of contributing
- Rational peer:
 - Contribute if $\theta_i > 1/x$
 - Free-ride otherwise

Contributions with no incentive mechanism

- Assume uniform distribution of types

Contributions with no incentive mechanism (2)

- Equilibria stability

Contributions with no incentive mechanism (3)

- Equilibria computation

Contributions with no incentive mechanism (4)

- Result: The highest stable equilibrium contribution level x_1 increases with θ_m and converges to one as θ_m goes to infinity but falls to zero if $\theta_m < 4$
- Remark: if the distribution is not uniform: the graphical method still applies

Overall system performance

- $W = ax - (1/x)x = ax - 1$
- Even if participation provides high benefits, the system may collapse

Reputation and service differentiation in P2P

- Consider a reputation system that can catch free-riders with probability p and exclude them
 - Alternatively: catch all free-riders and give them service altered by $(1-p)$
- Two effects
 - Load reduced, hence cost reduced
 - Penalty introduces a threat

Equilibrium with reputation

- Q: individual benefit
- R: reduced contribution
- T: threat

Equilibrium with reputation (2)

System performance with reputation

- $W = x(Q-R) + (1-x)(Q-T) = (ax-1)(x + (1-x)(1-p))$
- Trade-off: Penalty on free riders increases x but entails social cost
- If $p > 1/a$, the threat is larger than the cost
→ No free rider, optimal system performance $a-1$

FOX (Fair Optimal eXchange)

- Theoretical approach
- Assumes all peer are homogeneous, with capacity to serve k requests in parallel and seek to minimize completion time
- FOX: distributed synchronized protocol giving the optimum
 - i.e., all peers can achieve optimum if they comply
- “grim trigger” strategy: each peer can collapse the system if he finds a deviating neighbor

FOX equilibrium

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Hidden actions

- In P2P, many strategic actions are not directly observable
 - Arrival/departure
 - Message forwarding
- Same with many other contexts
 - Packet forwarding in ad-hoc networks
 - Worker's effort
- Moral hazard: situation in which a party is more willing to take a risk knowing that the cost will be supported (at least in part) by others
 - E.g., insurance

Principal-agent model

- A principal employs a set of n agents: $N = \{1, \dots, n\}$
- Action set $A_i = \{0, 1\}$
- Cost $c(0)=0$, $c(1)=c>0$
- The actions of agents determine (probabilistically) an outcome o in $\{0, 1\}$
- Principal valuation of success: $v>0$ (no gain in case of failure)
- Technology (or success function) $t(a_1, \dots, a_n)$: probability of success
- Remark: many different models exist
 - One agent, different action sets
 - Etc.

Read-once networks

- One graph with 2 special nodes: source and sink
- Each agent controls 1 link
- Agents action:
 - low effort \rightarrow succeed with probability γ in $(0, 1/2)$
 - High effort \rightarrow succeed with probability $1-\gamma$ in $(1/2, 1)$
- The project succeeds if there is a successful source-sink path

Example

- AND technology
- OR technology

Contract

- The principal agent can design a “contract”
 - Payment of $p_i \geq 0$ upon success
 - Nothing upon failure

- The agents are in a game:

$$u_i(a) = p_i t(a) - c(a_i)$$

- The principal wants to design a contract such that his expected profit is maximized

$$u(a, v) = t(a) \cdot \left(v - \sum_{i \in N} p_i \right)$$

Definitions and assumptions

- Assumptions:
 - $t(1, a_{-i}) > t(0, a_{-i})$ for all a_{-i}
 - $t(a) > 0$ for all a
- Definition: the marginal contribution of agent i given a_{-i} is

$$\Delta_i(a_{-i}) = t(1, a_{-i}) - t(0, a_{-i})$$

- Increase in success probability due to i 's effort

Individual best response

- Given a_{-i} , agent's i best strategy is

$$a_i = 1 \quad \text{if} \quad p_i \geq \frac{c}{\Delta_i(a_{-i})}$$

$$a_i = 0 \quad \text{if} \quad p_i \leq \frac{c}{\Delta_i(a_{-i})}$$

Best contract inducing a

- The best contract for the principal that induces a as an equilibrium consists in
 - $p_i = 0$ for the agents choosing $a_i=0$
 - $p_i = \frac{c}{\Delta_i(a_{-i})}$ for the agents choosing $a_i=1$

Best contract inducing a (2)

- With this best contract, expected utilities are
 - $u_i = 0$ for the agents choosing $a_i=0$
 - $u_i = c \cdot \left(\frac{t(1, a_{-i})}{\Delta_i(a_{-i})} - 1 \right)$ for the agents choosing $a_i=1$
 - $u(a, v) = t(a) \cdot \left(v - \sum_{i:a_i=1} \frac{c}{\Delta_i(a_{-i})} \right)$ for the principal

Principal's objective

- Choosing the actions profile a^* that maximizes his utility $u(a, v)$
- Equivalent to choosing the set S^* of agents with $a_i=1$
- Depends on $v \rightarrow S^*(v)$
- We say that the principal contracts with i if $a_i=1$

Hidden vs observable actions

- Hidden actions: $u(a, v) = t(a) \cdot \left(v - \sum_{i: a_i=1} \frac{c}{\Delta_i(a_{-i})} \right)$

$$u_i = c \cdot \left(\frac{t(1, a_{-i})}{\Delta_i(a_{-i})} - 1 \right) \text{ if } a_i=1 \text{ and } 0 \text{ otherwise}$$

- If actions were observable
 - Give $p_i=c$ to high-effort agents regardless of success
 - Yields for the principal a utility equal to social welfare

$$u(a, v) = t(a) \cdot v - \sum_{i: a_i=1} c$$

→ Choose a to maximize social welfare

(POU) Price of Unaccountability

- $S^*(v)$: optimal contract in hidden case
- $S_0^*(v)$: optimal contract in observable case
- Definition: the $POU(t)$ of a technology t is defined as the worst-case ratio over v of the principal's utility in the observable and hidden actions cases

$$POU(t) = \sup_{v>0} \frac{t(S_0^*(v)) \cdot v - \sum_{i \in S_0^*(v)} c}{t(S^*(v)) \cdot \left(v - \sum_{i \in S^*(v)} \frac{c}{t(S^*(v)) - t(S^*(v) \setminus \{i\})} \right)}$$

Remark

- $\text{POU}(t) > 1$

Optimal contract

- We want to answer the questions:
- How to select the optimal contract (i.e., the optimal set of contracting agents)?
- How does it change with the principal's valuation v ?

Monotonicity

- The optimal contracts weakly improves when v increases:
 - For any technology, in both the hidden- and observable-actions cases, the expected utility of the principal, the success probability and the expected payment of the optimal contract are all non-decreasing when v increases

Proof

Proof (2)

Consequences

- Anonymous technology: the success probability is symmetric in the players
- For technologies for which the success probability depends only on the number of contracted agents (e.g. AND, OR), the number of contracted agents is non-decreasing when v increases

Optimal contract for the AND technology

- Theorem: For any anonymous AND technology with $\gamma = \gamma_i = 1 - \delta_i$ for all i
 - There exists a valuation finite v_* such that for any $v < v_*$, it is optimal to contract with no agent and for any $v > v_*$, it is optimal to contract with all agents (for $v = v_*$, both contracts are optimal)
 - The price of unaccountability is

$$POU = \left(\frac{1}{\gamma} - 1 \right)^{n-1} + \left(1 - \frac{\gamma}{1 - \gamma} \right)$$

Remarks

- Proof in M. Babaioff, M. Feldman and N. Nisan, “Combinatorial Agency”, in Proceedings of EC 2006.
- POU is not bounded!
 - Monitoring can be beneficial, even if costly

Example

- $n=2, c=1, \gamma=1/4$
- Compute for all number of agents
 - t
 - Δ
 - Utility of principal

Optimal contract for the OR technology

- Theorem: For any anonymous OR technology with $\gamma = \gamma_i = 1 - \delta_i$ for all i
 - There exist finite positive values v_1, \dots, v_n such that for any v in (v_k, v_{k+1}) , it is optimal to contract k agent. (For $v < v_0$, it is optimal to contract 0 agent, for $v > v_n$, it is optimal to contract n agent and for $v = v_k$, the principal is indifferent between contracting $k-1$ or k agents.)
 - The price of unaccountability is upper bounded by $5/2$

Example

- $n=2, c=1, \gamma=1/4$
- Compute for all number of agents
 - t
 - Δ
 - Utility of principal

Illustration

- Number of contracted agents

