

# Basis for automated proof: First-Order Resolution

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March 2023

# Plan

Introduction

Clausal form

Unification

First-Order Resolution

Completeness

Conclusion

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# Idea

Skolemization yields formulae without quantifiers.

Then we must find an insatisfiable set of instances, either by trial and error or by exhaustive enumeration.

This lecture presents a generalization of resolution to first-order logic:

- ▶ **Clausal form** of skolemized formulae
- ▶ **Resolution** over clauses **with variables**
- ▶ **Correctness** and **completeness** of the method

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# Litteral, clause

## Definition 5.2.19

A **positive litteral** is an atomic formula. Eg:  $P(x, y)$

A **negative litteral** is the negation of an atomic formula. Eg:  $\neg Q(a)$

A **clause** is a disjunction of litterals. Eg:  $P(x, y) \vee \neg Q(a)$

## Clausal form of a formula

### Definition 5.2.20

The **clausal form of a closed formula  $A$**  is obtained in two steps:

1. Skolemize  $A$  (which yields a normal form without quantifiers)
2. Distribute  $\vee$  over  $\wedge$  to get a set of clauses  $\Gamma$

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2. Distribute  $\vee$  over  $\wedge$  to get a set of clauses  $\Gamma$

### Property 5.2.21

$\forall(\Gamma)$  has a model if and only if  $A$  has a model. More precisely:

- ▶  $A$  is a consequence of  $\forall(\Gamma)$
- ▶ If  $A$  has a model, then  $\forall(\Gamma)$  has a model

**Proof:** We already know that skolemization preserves satisfiability. Then, distributivity yields a formula equivalent to the Skolem form.



## Clausal form of a set of formulae

### Definition 5.2.22

Let  $\Gamma = A_1, \dots, A_n$  be a set of closed formulae.

The **clausal form of  $\Gamma$**  is the union of the clausal forms of  $A_1, \dots, A_n$ , **paying attention, in the course of skolemization, to use a new symbol for each eliminated  $\exists$ .**

### Corollary 5.2.23

Let  $\Gamma$  be a set of closed formulae and  $\Delta$  its clausal form:

- ▶  $\Gamma$  is a consequence of  $\forall(\Delta)$
- ▶ if  $\Gamma$  has a model  $\exists$  then  $\forall(\Delta)$  has a model.

## Adapting Herbrand's theorem to clausal forms

### Theorem 5.2.24

Let  $\Gamma$  be a set of closed formulae and  $\Delta$  its clausal form:

$\Gamma$  is unsatisfiable

*if and only if*

there exists a finite unsatisfiable subset of instances of clauses of  $\Delta$ .

Proof.

- ▶ Skolemization preserves satisfiability
- ▶ Then we apply Herbrand's theorem to  $\forall(\Delta)$

□

## Example 5.2.25

Let  $A = \exists y \forall z (P(z, y) \Leftrightarrow \neg \exists x (P(z, x) \wedge P(x, z)))$ . We compute the clausal form of  $A$ .

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1-4. The four steps of Skolemization yield:

$$(\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)) \wedge (P(z, f(z)) \wedge P(f(z), z) \vee P(z, a))$$

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$$(\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)) \wedge (P(z, f(z)) \wedge P(f(z), z) \vee P(z, a))$$

5. The clausal form is the following set of clauses:

- ▶  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
- ▶  $C_2 = P(z, f(z)) \vee P(z, a)$
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- ▶  $C_1$  with  $x := a, z := f(a)$ , we get  $C''_1 = \neg P(f(a), a) \vee \neg P(a, f(a))$

This set of instances is unsatisfiable, thus  **$A$  is unsatisfiable !**

## In practice

Let  $\Gamma$  be a set of clauses. We want to prove that  $\forall(\Gamma)$  has no model.

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We use a formal system of “factorization, copy, binary resolution” to infer  $\perp$  from  $\Gamma$ .

Completeness of these rules is based on Herbrand's Theorem.  
Unification is used to find suitable instances of these clauses.

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## John Alan Robinson (1930-2016)

- ▶ developed the **resolution principle**
- ▶ **unification** algorithm (1965)
  - ▶ makes the search for contradictory instances efficient
  - ▶ special case of *matching* used in functional programming
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```
parent(pascal, mathilde).
brother(stephane, pascal).
uncle(X,Y) :- parent(Z,Y),
              brother(X,Z).
?- uncle(stephane, mathilde).
true.
```

(Prolog, Colmerauer & Roussel, 1972)

# Unification: expression, solution

## Definition 5.3.1

- ▶ A term or a literal is an **expression**.
- ▶ A substitution  $\sigma$  is a **solution of equation**  $e_1 = e_2$  if  $e_1\sigma$  and  $e_2\sigma$  are syntactically **identical**.
- ▶ A substitution is a **solution of a set of equations** if it is a solution of each equation in the set.

## Unification: example 5.3.4

The equation  $P(x, f(y)) = P(g(z), z)$  has the solution :

The set of equations  $x = g(z), f(y) = z$  has the solution :

## Unification: example 5.3.4

The equation  $P(x, f(y)) = P(g(z), z)$  has the solution :

$$x := g(f(y)), z := f(y)$$

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## Unification: composition of substitutions

### Definition 5.3.5

- ▶ Let  $\sigma$  and  $\tau$  be two substitutions, we note  $\sigma\tau$  the substitution such that for all variable  $x$ ,  $x\sigma\tau = (x\sigma)\tau$ .
- ▶ The substitution  $\sigma\tau$  is **an instance of  $\sigma$** .
- ▶ Two substitutions are **equivalent** if each of them is an instance of the other.

## Unification: example 5.3.6

Consider substitutions

- ▶  $\sigma_1 = \langle x := g(z), y := z \rangle$
- ▶  $\sigma_2 = \langle x := g(y), z := y \rangle$
- ▶  $\sigma_3 = \langle x := g(a), y := a, z := a \rangle$

We have the following relations between these substitutions:

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- ▶  $\sigma_1 = \sigma_2 \langle y := z \rangle$
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$$\text{▶ } \sigma_1 = \sigma_2 \langle y := z \rangle$$

$$\text{▶ } \sigma_2 = \sigma_1 \langle z := y \rangle$$

$\sigma_1$  and  $\sigma_2$  are equivalent.

$$\text{▶ } \sigma_3 = \sigma_1 \langle z := a \rangle$$

$$\text{▶ } \sigma_3 = \sigma_2 \langle y := a \rangle$$

$\sigma_3$  is an instance of  $\sigma_1$  as well as of  $\sigma_2$ , but is equivalent to neither of them.

## Unification: definition of the most general solution

### Definition 5.3.7 (mgu)

A solution of a set of equations is said to be **the most general** if any other solution is an instance of it.

Note that two “most general” solutions are equivalent.

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### Example 5.3.8

Consider the equation  $f(x, g(z)) = f(g(y), x)$ .

- ▶  $\sigma_1 = \langle x := g(z), y := z \rangle$
- ▶  $\sigma_2 = \langle x := g(y), z := y \rangle$
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are 3 solutions.

$\sigma_1$  and  $\sigma_2$  are its **most general** solutions.

# Unifier

## Definition 5.3.2

Let  $E$  be a set of expressions and  $E\sigma = \{t\sigma \mid t \in E\}$ .

$\sigma$  is a **unifier of  $E$**  if and only if the set  $E\sigma$  has only one element.

If  $E = \{e_1, \dots, e_n\}$ , another way of writing this is that

$\sigma$  is a solution of the set of equations 
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The notion of **most general unifier** (or principal unifier) extends to this definition.

## Unification algorithm: a sketch

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- ▶ equations **to be solved**, denoted by  $=$
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Initially, there is no solved equations.

The algorithm transforms a system into an equivalent system and stops when :

- ▶ every equation is solved:  
then the list of solved equations is the most general solution
- ▶ or when it claims that there is no solution.

## Unification algorithm: the rules

Choose an equation **yet to be solved** then:

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2. **Decompose**
  - ▶  $\neg A = \neg B$  becomes  $A = B$
  - ▶  $f(s_1, \dots, s_n) = f(t_1, \dots, t_n)$  becomes  $s_1 = t_1, \dots, s_n = t_n$ .  
(nothing if  $f$  is a constant)

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(nothing if  $f$  is a constant)

3. **Failure of decomposition**

If an equation is of the form  $f(s_1, \dots, s_n) = g(t_1, \dots, t_p)$  with  $f \neq g$  then the algorithm claims that there is no solution.

(in particular is the equation is  $\neg A = B$  with  $B$  a positive literal)

## Unification: algorithm (rules)

### 4. **Orient**

If an equation is  $t = x$  where  $t$  is a (true) term and  $x$  is a variable, then we replace the equation with  $x = t$ .

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### 5. Elimination of a variable

If an equation is  $x = t$  where  $x$  is a variable and  $t$  is a term **without any occurrence** of  $x$

- ▶ remove it from the equations to be solved
- ▶ replace  $x$  by  $t$  in **every** equation (unsolved **and** solved)
- ▶ add  $x := t$  to the solved equations

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### 6. Failure of elimination

If an equation is  $x = t$  where  $x$  is a variable and  $t$  **contains**  $x$  then the algorithm claims that there is no solution.

## Unification: algorithm (example 5.3.11)

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2. Solve  $f(x, x, a) = f(g(y), g(a), y)$ .

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Decomposition

$x = g(y), x = g(a), a = y$

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Elimination of  $x$   $x := g(y), g(z) = g(y)$

Decomposition  $x := g(y), z = y$

Elimination of  $z$   $x := g(y), z := y$  **solution**

2. Solve  $f(x, x, a) = f(g(y), g(a), y)$ .

Decomposition  $x = g(y), x = g(a), a = y$

Elimination of  $x$  in the 1st equation  $x := g(y), g(y) = g(a), a = y$

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Decomposition  $x = g(y), g(z) = x$

Elimination of  $x$   $x := g(y), g(z) = g(y)$

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Elimination of  $z$   $x := g(y), z := y$  **solution**

2. Solve  $f(x, x, a) = f(g(y), g(a), y)$ .

Decomposition  $x = g(y), x = g(a), a = y$

Elimination of  $x$  in the 1st equation  $x := g(y), g(y) = g(a), a = y$

Decomposition  $x := g(y), y = a, a = y$

## Unification: algorithm (example 5.3.11)

1. Solve  $f(x, g(z)) = f(g(y), x)$ .

Decomposition  $x = g(y), g(z) = x$

Elimination of  $x$   $x := g(y), g(z) = g(y)$

Decomposition  $x := g(y), z = y$

Elimination of  $z$   $x := g(y), z := y$  **solution**

2. Solve  $f(x, x, a) = f(g(y), g(a), y)$ .

Decomposition  $x = g(y), x = g(a), a = y$

Elimination of  $x$  in the 1st equation  $x := g(y), g(y) = g(a), a = y$

Decomposition  $x := g(y), y = a, a = y$

Elimination of  $y$   $x := g(a), y := a, a = a$

## Unification: algorithm (example 5.3.11)

1. Solve  $f(x, g(z)) = f(g(y), x)$ .

Decomposition  $x = g(y), g(z) = x$

Elimination of  $x$   $x := g(y), g(z) = g(y)$

Decomposition  $x := g(y), z = y$

Elimination of  $z$   $x := g(y), z := y$  **solution**

2. Solve  $f(x, x, a) = f(g(y), g(a), y)$ .

Decomposition  $x = g(y), x = g(a), a = y$

Elimination of  $x$  in the 1st equation  $x := g(y), g(y) = g(a), a = y$

Decomposition  $x := g(y), y = a, a = y$

Elimination of  $y$   $x := g(a), y := a, a = a$

Removal  $x := g(a), y := a$  **solution**



## Unification: algorithm (example 5.3.11)

3. Solve  $f(x, x, x) = f(g(y), g(a), y)$ .

Decomposition       $x = g(y), x = g(a), x = y$

## Unification: algorithm (example 5.3.11)

3. Solve  $f(x, x, x) = f(g(y), g(a), y)$ .

Decomposition  $x = g(y), x = g(a), x = y$

Elimination of  $x$   $x := g(y), g(y) = g(a), g(y) = y$

## Unification: algorithm (example 5.3.11)

3. Solve  $f(x, x, x) = f(g(y), g(a), y)$ .

Decomposition	$x = g(y), x = g(a), x = y$
Elimination of $x$	$x := g(y), g(y) = g(a), g(y) = y$
Orienting	$x := g(y), g(y) = g(a), y = g(y)$

## Unification: algorithm (example 5.3.11)

3. Solve  $f(x, x, x) = f(g(y), g(a), y)$ .

Decomposition	$x = g(y), x = g(a), x = y$
Elimination of $x$	$x := g(y), g(y) = g(a), g(y) = y$
Orienting	$x := g(y), g(y) = g(a), y = g(y)$
Elimination failure	there is no solution

## Unification: algorithm (example 5.3.11)

3. Solve  $f(x, x, x) = f(g(y), g(a), y)$ .

Decomposition	$x = g(y), x = g(a), x = y$
Elimination of $x$	$x := g(y), g(y) = g(a), g(y) = y$
Orienting	$x := g(y), g(y) = g(a), y = g(y)$
Elimination failure	there is no solution

**Remark:** correctness and termination proofs for unification algorithm are in the handout course notes.

# Plan

Introduction

Clausal form

Unification

**First-Order Resolution**

Completeness

Conclusion

## Three rules (examples)

### 1. Factorization

$$\frac{P(x, x) \vee P(y, a) \vee Q(y)}{P(a, a) \vee Q(a)}$$

### 2. Copy

$$\frac{P(x, y)}{P(u, v)}$$

### 3. Binary resolution

$$\frac{Q(x) \vee P(x, a) \quad \neg P(b, y) \vee R(f(y))}{Q(b) \vee R(f(a))}$$

## Three rules (examples)

### 1. Factorization

$$\frac{P(x, x) \vee P(y, a) \vee Q(y)}{P(a, a) \vee Q(a)} \quad \text{unification}$$

### 2. Copy

$$\frac{P(x, y)}{P(u, v)}$$

### 3. Binary resolution

$$\frac{Q(x) \vee P(x, a) \quad \neg P(b, y) \vee R(f(y))}{Q(b) \vee R(f(a))} \quad \text{unification}$$



# Factorization

## Definition 5.4.2

The clause  $C'$  is a **factor** of clause  $C$  if:

- ▶ either  $C' = C$
- ▶ or  $C' = C\sigma$

where  $\sigma$  is the most general unifier of at least two literals in  $C$ .

## Example 5.4.3

The clause  $\underline{P(x)} \vee Q(g(x, y)) \vee \underline{P(f(a))}$  has two factors :

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The clause  $\underline{P(x)} \vee Q(g(x, y)) \vee \underline{P(f(a))}$  has two factors :

- ▶ itself
- ▶  $P(f(a)) \vee Q(g(f(a), y))$  obtained by applying  $x := f(a)$

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## Example 5.4.3

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- ▶ itself
- ▶  $P(f(a)) \vee Q(g(f(a), y))$  obtained by applying  $x := f(a)$

## Property 5.4.4

Let  $C'$  be a factor of  $C$ : then  $\forall(C) \models \forall(C')$ .

**Proof:** Actually  $\forall(A) \models \forall(A\sigma)$  for any formula  $A$  and any substitution  $\sigma$ .

# Copy

## Definition 5.4.5

Let  $\sigma$  be a substitution which:

- ▶ changes only variables **into variables**
- ▶ is a **bijection**

The clause  $C\sigma$  is a **copy** of the clause  $C$ .

We also say that  $\sigma$  is a **renaming** of  $C$ .

# Copy

## Definition 5.4.5

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- ▶ changes only variables **into variables**
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The clause  $C\sigma$  is a **copy** of the clause  $C$ .

We also say that  $\sigma$  is a **renaming** of  $C$ .

## Example 5.4.7

Let  $\sigma = \langle x := u, y := v \rangle$ .

The literal  $P(u, v)$  is a **copy** of  $P(x, y)$ .

Note that  $P(x, y)$  is also a copy of  $P(u, v)$

by the renaming  $\tau = \langle u := x, v := y \rangle$ , the **inverse of the renaming**  $\sigma$ .

# Copy

## Property 5.4.8

If  $\sigma$  is a renaming of  $C$ , then  $C$  is also a copy of  $C\sigma$ .

## Proof.

It is easy to prove that  $\sigma^{-1}$  is a renaming of  $C\sigma$ . □

## Property 5.4.9

If  $C$  and  $C'$  are copies of each other, then  $\forall(C) \equiv \forall(C')$ .

## Proof.

$C$  and  $C'$  are instances of each other.

Thus  $\forall(C) \equiv \forall(C')$  and conversely. □

## Binary resolvent

### Definition 5.4.10

Let  $C$  and  $D$  be two clauses **without common variables**.

If there are two literals:

- ▶  $L \in C$
- ▶  $M \in D$
- ▶ such that  $L$  and  $M^c$  are unifiable
- ▶  $\sigma$  is the most general solution of the equation  $L = M^c$

then  $E = ((C - \{L\}) \cup (D - \{M\}))\sigma$  is a **binary resolvent** of  $C$  and  $D$ .

# Binary resolvent

## Example 5.4.11

Let  $C = P(x, y) \vee P(y, k(z))$  and  $D = \neg P(a, f(a, y_1))$ .



## Binary resolvent

### Example 5.4.11

Let  $C = P(x, y) \vee P(y, k(z))$  and  $D = \neg P(a, f(a, y_1))$ .

$\langle x := a, y := f(a, y_1) \rangle$  is the most general solution of  
 $P(x, y) = P(a, f(a, y_1))$

The (only) binary resolvent is  $P(f(a, y_1), k(z))$ .

## Binary resolvent

### Example 5.4.11

Let  $C = P(x, y) \vee P(y, k(z))$  and  $D = \neg P(a, f(a, y_1))$ .

$\langle x := a, y := f(a, y_1) \rangle$  is the most general solution of  
 $P(x, y) = P(a, f(a, y_1))$

The (only) binary resolvent is  $P(f(a, y_1), k(z))$ .

### Property 5.4.12

Let  $E$  be a resolvent binary of clauses  $C$  and  $D : \forall(C), \forall(D) \models \forall(E)$ .

# Resolution:

## Definition 5.4.13

A **proof** of  $C$  from  $\Gamma$  is a sequence of clauses where each clause is:

- ▶ a member of  $\Gamma$ ,
- ▶ or a factor of a previous clause in the proof,
- ▶ or a copy of a previous clause in the proof,
- ▶ or a binary resolvent of 2 previous clauses in the proof.

terminated by  $C$ .

$C$  is **first-order inferred from  $\Gamma$** , denoted by  $\Gamma \vdash_{1fb} C$ .

# Resolution:

## Definition 5.4.13

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terminated by  $C$ .

$C$  is **first-order inferred from  $\Gamma$** , denoted by  $\Gamma \vdash_{fcb} C$ .

Property 5.4.14: **consistency**

If  $\Gamma \vdash_{fcb} C$  then  $\forall(\Gamma) \models \forall(C)$

By induction, using the consistency of the three rules.

## Resolution: Example 5.4.15

Given the two clauses

1.  $C_1 = P(x, y) \vee P(y, x)$

2.  $C_2 = \neg P(u, z) \vee \neg P(z, u)$

Show by resolution that  $\forall(C_1, C_2)$  has no model.

## Resolution: Example 5.4.15

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Show by resolution that  $\forall(C_1, C_2)$  has no model.

1.  $P(x, y) \vee P(y, x)$       Hyp  $C_1$

## Resolution: Example 5.4.15

Given the two clauses

1.  $C_1 = P(x, y) \vee P(y, x)$
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Show by resolution that  $\forall(C_1, C_2)$  has no model.

- |    |                        |                                      |
|----|------------------------|--------------------------------------|
| 1. | $P(x, y) \vee P(y, x)$ | Hyp $C_1$                            |
| 2. | $P(y, y)$              | Factor of 1 $\langle x := y \rangle$ |

## Resolution: Example 5.4.15

Given the two clauses

1.  $C_1 = P(x, y) \vee P(y, x)$
2.  $C_2 = \neg P(u, z) \vee \neg P(z, u)$

Show by resolution that  $\forall(C_1, C_2)$  has no model.

1.  $P(x, y) \vee P(y, x)$  Hyp  $C_1$
2.  $P(y, y)$  Factor of 1  $\langle x := y \rangle$
3.  $\neg P(u, z) \vee \neg P(z, u)$  Hyp  $C_2$



## Resolution: Example 5.4.15

Given the two clauses

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Show by resolution that  $\forall(C_1, C_2)$  has no model.

- |    |                                  |             |                          |
|----|----------------------------------|-------------|--------------------------|
| 1. | $P(x, y) \vee P(y, x)$           | Hyp $C_1$   |                          |
| 2. | $P(y, y)$                        | Factor of 1 | $\langle x := y \rangle$ |
| 3. | $\neg P(u, z) \vee \neg P(z, u)$ | Hyp $C_2$   |                          |
| 4. | $\neg P(z, z)$                   | Factor of 3 | $\langle u := z \rangle$ |

## Resolution: Example 5.4.15

Given the two clauses

1.  $C_1 = P(x, y) \vee P(y, x)$
2.  $C_2 = \neg P(u, z) \vee \neg P(z, u)$

Show by resolution that  $\forall(C_1, C_2)$  has no model.

- |    |                                  |  |
|----|----------------------------------|--|
| 1. | $P(x, y) \vee P(y, x)$           | Hyp $C_1$                                      |
| 2. | $P(y, y)$                        | Factor of 1 $\langle x := y \rangle$           |
| 3. | $\neg P(u, z) \vee \neg P(z, u)$ | Hyp $C_2$                                      |
| 4. | $\neg P(z, z)$                   | Factor of 3 $\langle u := z \rangle$           |
| 5. | $\perp$                          | Binary Resolvent 2, 4 $\langle y := z \rangle$ |

## Resolution: Example 5.4.15

Given the two clauses

1.  $C_1 = P(x, y) \vee P(y, x)$
2.  $C_2 = \neg P(u, z) \vee \neg P(z, u)$

Show by resolution that  $\forall(C_1, C_2)$  has no model.

1.	$P(x, y) \vee P(y, x)$	Hyp $C_1$
2.	$P(y, y)$	Factor of 1 $\langle x := y \rangle$
3.	$\neg P(u, z) \vee \neg P(z, u)$	Hyp $C_2$
4.	$\neg P(z, z)$	Factor of 3 $\langle u := z \rangle$
5.	$\perp$	Binary Resolvent 2, 4 $\langle y := z \rangle$

This example shows, a contrario, that binary resolution alone is incomplete: without factorization, the empty clause cannot be inferred.

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$

2.  $C_2 = P(z, f(z)) \vee P(z, a)$

3.  $C_3 = P(f(z), z) \vee P(z, a)$

1.  $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$       Hyp  $C_1$

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$

2.  $C_2 = P(z, f(z)) \vee P(z, a)$

3.  $C_3 = P(f(z), z) \vee P(z, a)$

1.  $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  Hyp  $C_1$

2.  $P(z, f(z)) \vee P(z, a)$  Hyp  $C_2$

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |   |                                 |
|---|---------------------------------|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$ | Hyp $C_1$                       |
| 2. $P(z, f(z)) \vee P(z, a)$                          | Hyp $C_2$                       |
| 3. $P(v, f(v)) \vee P(v, a)$                          | Copy 2 $\langle z := v \rangle$ |

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |  |  |
|--|--|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  | Hyp $C_1$                                      |
| 2. $P(z, f(z)) \vee P(z, a)$                           | Hyp $C_2$                                      |
| 3. $P(v, f(v)) \vee P(v, a)$                           | Copy 2 $\langle z := v \rangle$                |
| 4. $\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$ | BR 1(3), 3(1) $\langle z:=f(v) ; x:=v \rangle$ |



## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |  |  |
|--|--|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  | Hyp $C_1$  |
| 2. $P(z, f(z)) \vee P(z, a)$                           | Hyp $C_2$  |
| 3. $P(v, f(v)) \vee P(v, a)$                           | Copy 2 $\langle z := v \rangle$                    |
| 4. $\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$ | BR 1(3), 3(1) $\langle z := f(v) ; x := v \rangle$ |
| 5. $\neg P(f(a), a) \vee P(a, a)$                      | Fact 4 $\langle v := a \rangle$                    |

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |  |  |
|--|--|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  | Hyp $C_1$  |
| 2. $P(z, f(z)) \vee P(z, a)$                           | Hyp $C_2$  |
| 3. $P(v, f(v)) \vee P(v, a)$                           | Copy 2 $\langle z := v \rangle$                    |
| 4. $\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$ | BR 1(3), 3(1) $\langle z := f(v) ; x := v \rangle$ |
| 5. $\neg P(f(a), a) \vee P(a, a)$                      | Fact 4 $\langle v := a \rangle$                    |
| 6. $P(f(z), z) \vee P(z, a)$                           | Hyp $C_3$  |

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |  |  |
|--|--|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  | Hyp $C_1$  |
| 2. $P(z, f(z)) \vee P(z, a)$                           | Hyp $C_2$  |
| 3. $P(v, f(v)) \vee P(v, a)$                           | Copy 2 $\langle z := v \rangle$                    |
| 4. $\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$ | BR 1(3), 3(1) $\langle z := f(v) ; x := v \rangle$ |
| 5. $\neg P(f(a), a) \vee P(a, a)$                      | Fact 4 $\langle v := a \rangle$                    |
| 6. $P(f(z), z) \vee P(z, a)$                           | Hyp $C_3$  |
| 7. $P(a, a)$   | BR 5(1), 6(1) $\langle z := a \rangle$             |

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

- |  |  |
|--|--|
| 1. $\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$  | Hyp $C_1$  |
| 2. $P(z, f(z)) \vee P(z, a)$                           | Hyp $C_2$  |
| 3. $P(v, f(v)) \vee P(v, a)$                           | Copy 2 $\langle z := v \rangle$                    |
| 4. $\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$ | BR 1(3), 3(1) $\langle z := f(v) ; x := v \rangle$ |
| 5. $\neg P(f(a), a) \vee P(a, a)$                      | Fact 4 $\langle v := a \rangle$                    |
| 6. $P(f(z), z) \vee P(z, a)$                           | Hyp $C_3$  |
| 7. $P(a, a)$   | BR 5(1), 6(1) $\langle z := a \rangle$             |
| 8. $\neg P(a, a)$                                      | Fact 1 $\langle x := a ; z := a \rangle$           |

## Resolution: Example 5.4.16

1.  $C_1 = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$
2.  $C_2 = P(z, f(z)) \vee P(z, a)$
3.  $C_3 = P(f(z), z) \vee P(z, a)$

1.	$\neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$	Hyp $C_1$
2.	$P(z, f(z)) \vee P(z, a)$	Hyp $C_2$
3.	$P(v, f(v)) \vee P(v, a)$	Copy 2 $\langle z := v \rangle$
4.	$\neg P(f(v), a) \vee \neg P(f(v), v) \vee P(v, a)$	BR 1(3), 3(1) $\langle z := f(v) ; x := v \rangle$
5.	$\neg P(f(a), a) \vee P(a, a)$	Fact 4 $\langle v := a \rangle$
6.	$P(f(z), z) \vee P(z, a)$	Hyp $C_3$
7.	$P(a, a)$	BR 5(1), 6(1) $\langle z := a \rangle$
8.	$\neg P(a, a)$	Fact 1 $\langle x := a ; z := a \rangle$
9.	$\perp$	BR 7, 8

# Plan

Introduction

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First-Order Resolution

**Completeness**

Conclusion

## First-Order resolution

We define a **new system** with only **one rule**, first-order resolution, which is a combination of factorization, copy and binary resolution.

### Definition 5.4.17

The clause  $E$  is a **first-order resolvent** of clauses  $C$  and  $D$  if:

- ▶  $E$  is a binary resolvent of  $C'$  and  $D'$ , where
- ▶  $C'$  is a factor of  $C$
- ▶  $D'$  is a copy of a factor of  $D$  without any common variable with  $C'$

$\frac{C \quad D}{E}$  is called **first-order resolution**.

## Example 5.4.18

Let  $C = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$   
and  $D = P(z, f(z)) \vee P(z, a)$ .



## Example 5.4.18

Let  $C = \neg P(z, a) \vee \neg P(z, x) \vee \neg P(x, z)$   
and  $D = P(z, f(z)) \vee P(z, a)$ .

- ▶  $C' = \neg P(a, a)$  is a factor of  $C$
- ▶  $D$  is a factor of itself (without any common variable with  $C'$ )
- ▶  $P(a, f(a))$  is a binary resolvent of  $C'$  and of  $D$

Thus it is a first-order resolvent of  $C$  and  $D$ .

## Three notions of proof by resolution

Let  $\Gamma$  be a set of clauses and  $C$  a clause.

### Notations

## Three notions of proof by resolution

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By definition we have :  $\Gamma \vdash_{1r} C$  implies  $\Gamma \vdash_{1fcb} C$

## Lifting theorem (1/3)

### Theorem 5.4.19

Let  $C'$  and  $D'$  be instances of  $C$  and  $D$ .

Let  $E'$  be a **propositional** resolvent of  $C'$  and  $D'$ .

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- ▶  $E = P(x) \vee \neg Q(x)$  is a first-order resolvent of  $C$  and  $D$  having  $E'$  as an instance.

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Let  $\Delta$  be a set of **instances** of clauses from  $\Gamma$ .

Let  $C_1, \dots, C_n$  be a proof by **propositional** resolution from  $\Delta$ .

There exists a proof  $D_1, \dots, D_n$  by **first-order resolution** from  $\Gamma$  such that each  $C_j$  is an instance of  $D_j$ .

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### Proof.

By induction on  $n$ . Let  $C_1, \dots, C_n, C_{n+1}$  be a proof by propositional resolution starting with  $\Delta$ . By induction, there exists a proof  $D_1, \dots, D_n$  by first-order resolution.

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2. If  $C_{n+1}$  is a propositional resolvent of  $C_j$  and  $C_k$ , we use the first-order resolvent of  $D_j$  and  $D_k$  from the previous theorem.

□

## Lifting theorem (3/3)

### Corollary 5.4.22

Let  $\Gamma$  be a set of clauses  
and  $\Delta$  a set of instances of clauses of  $\Gamma$ .

Suppose that  $\Delta \vdash_p C$ .

There exists  $D$  such that:

- ▶  $\Gamma \vdash_{1r} D$
- ▶  $C$  is an instance of  $D$ .

The proof of  $C$  from  $\Delta$  has been **lifted to a first-order proof**.



## Example 5.4.23

$$\Gamma = \{ P(f(x)) \vee P(u), \neg P(x) \vee Q(z), \neg Q(x) \vee \neg Q(y) \}.$$

$\forall(\Gamma)$  is unsatisfiable and we prove it in three different ways.

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1. **By instantiation on the Herbrand universe**  $a, f(a), f(f(a)), \dots$ :

$P(f(x)) \vee P(u)$	is instantiated to	$P(f(a))$
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$P(f(a))$	$\neg P(f(a)) \vee Q(a)$	$\neg Q(a)$
<hr/>		
	$Q(a)$	
<hr/>		
	$\perp$	

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$$P(f(x)) \vee P(u), \neg P(x) \vee Q(z), \neg Q(x) \vee \neg Q(y)$$

2. This proof by propositional resolution is **lifted to a proof by first-order resolution** :

$$\begin{array}{r}
 \frac{P(f(x)) \vee P(u) \quad \neg P(x) \vee Q(z)}{Q(z)} \quad \neg Q(x) \vee \neg Q(y) \\
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3. Each first-order resolution rule is **decomposed into factorization, copy and binary resolution**:

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3. Each first-order resolution rule **is decomposed into factorization, copy and binary resolution**:

$$\frac{\frac{\frac{P(f(x)) \vee P(u)}{P(f(x))} \text{ fact} \quad \frac{\neg P(x) \vee Q(z)}{\neg P(y) \vee Q(z)} \text{ copy}}{Q(z)} \text{ br} \quad \frac{\neg Q(x) \vee \neg Q(y)}{\neg Q(x)} \text{ fact}}{\perp} \text{ br}$$

# Refutational completeness of first-order resolution

## Theorem 5.4.24

The three propositions

1.  $\Gamma \vdash_{1r} \perp$
2.  $\Gamma \vdash_{1fcb} \perp$
3.  $\forall(\Gamma) \models \perp$

are equivalent.

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## Proof.

- ▶ (1  $\Rightarrow$  2) because first-order resolution is a combination of factorization, copy and binary resolution.

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- ▶  $(1 \Rightarrow 2)$  because first-order resolution is a combination of factorization, copy and binary resolution.
- ▶  $(2 \Rightarrow 3)$  because factorization, copy and binary resolution are consistent.

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- ▶ (1  $\Rightarrow$  2) because first-order resolution is a combination of factorization, copy and binary resolution.
- ▶ (2  $\Rightarrow$  3) because factorization, copy and binary resolution are consistent.
- ▶ (3  $\Rightarrow$  1). Suppose that  $\forall(\Gamma)$  is unsatisfiable.

By Herbrand's theorem, there is a finite unsatisfiable set  $\Delta$  of instances.

By completeness of propositional resolution, we have  $\Delta \vdash_p \perp$ .

By lifting,  $\Gamma \vdash_{1r} D$  where  $\perp$  is an instance of  $D$ ; hence  $D = \perp$ .

□

## Automated proofs

To produce automated proofs in binary resolution, one can use the software (working similarly to *complete strategy*):

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If the set of clauses is unsatisfiable, then the software can theoretically deduce the empty clause (given an unlimited amount of time).

What can we conclude ?

- ▶ if the software states that it has deduced the empty clause:
  - ▶ the clauses are unsatisfiable indeed
  - ▶ it provides a proof
- ▶ if the software states that it cannot prove the empty clause, or if it runs out of time:
  - ▶ nothing can be concluded

# Plan

Introduction

Clausal form

Unification

First-Order Resolution

Completeness

Conclusion

# Today

- ▶ **Unification** is an effective way of finding suitable instances of clauses with variables
- ▶ **First-order resolution** integrates in a single deductive system both the **search for unsatisfiable instances** and the **proof of unsatisfiability** of a set of clauses
- ▶ First-order resolution is **consistent and complete**, and one way to build a first-order proof is by **lifting** a propositional proof.

# Overview of the Semester

- ▶ Propositional logic
- ▶ Propositional resolution
- ▶ Natural deduction for propositional logic

## MIDTERM EXAM

- ▶ First order logic
- ▶ First-order resolution \*
- ▶ First-order natural deduction

## EXAM



# Next lecture

## First-order Natural Deduction

- ▶ Rules
- ▶ Examples